

The DUNE Grid Interface

An Introduction

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Part I

Dune Course: Design Principles

[...] a modular toolbox for solving partial differential equations (PDEs) with grid-based methods [...]

— <http://www.dune-project.org/>

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Contents

Design Principles

The DUNE Framework

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Flexibility: Separation of data structures and algorithms.

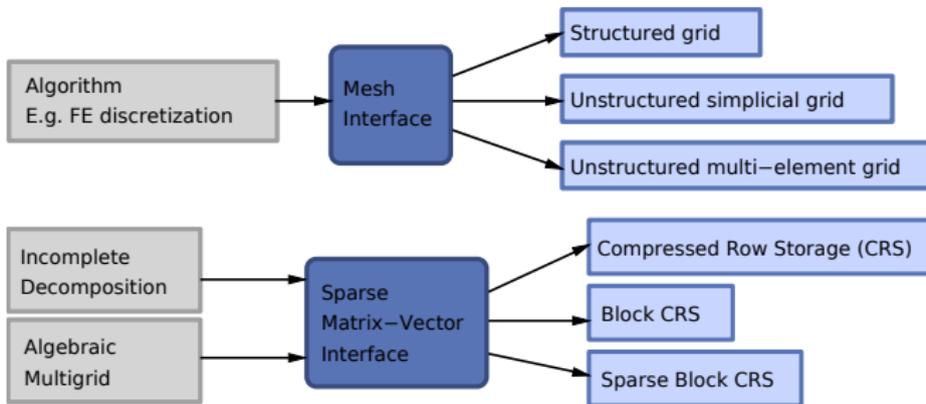
Efficiency: Generic programming techniques.

Legacy Code: Reuse existing finite element software.

Flexibility

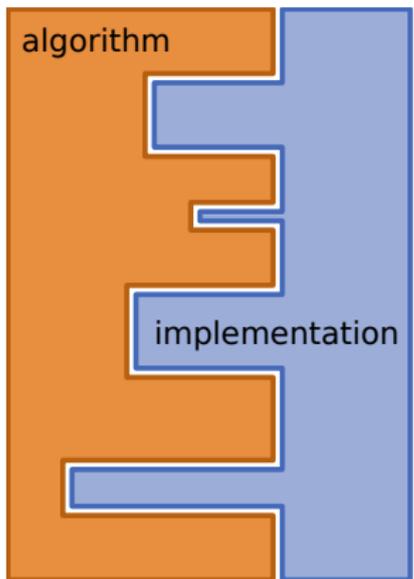
Separate data structures and algorithms.

- ▶ The algorithm determines the data structure to operate on.
- ▶ Data structures are hidden under a common interface.
- ▶ Algorithms work only on that interface.
- ▶ Different implementations of the interface.



Efficiency

Implementation with generic programming techniques.



1. Static Polymorphism
 - ▶ Engine Concept (see STL)
 - ▶ Curiously Recurring Template Pattern (Barton and Nackman)
2. Grid Entity Ranges
 - ▶ Generic access to different data structures.
3. View Concept
 - ▶ Access to different partitions of one data set.

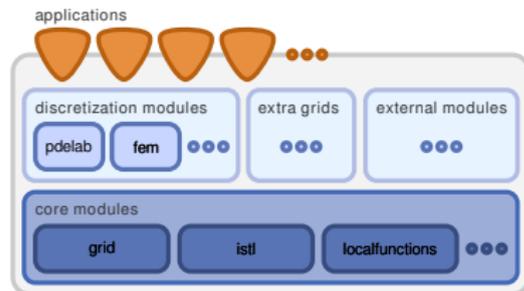
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Design Principles

The DUNE Framework

The DUNE Framework

- ▶ Modules
 - ▶ Code is split into separate modules.
 - ▶ Applications use only the modules they need.
 - ▶ Modules are sorted according to level of maturity.
 - ▶ Everybody can provide their own modules.
- ▶ Portability
- ▶ Open Development Process
- ▶ Free Software Licence



[Bastian, Blatt, Dedner, Engwer, Klöfkor, Kornhuber, Ohlberger, Sander 2008]

DUNE Release 2.4.1

Current stable version is 2.4.1,
available since February 29th 2015.

dune-common: foundation classes,
infrastructure

dune-geometry: geometric mappings,
quadrature rules visualization

dune-grid: grid interface,
visualization

dune-istl: (*Iterative Solver Template
Library*)

generic sparse matrix/vector
classes,
solvers (Krylov methods, AMG,
etc.)

dune-localfunctions: generic interface
for local finite element
functions. Abstract definition
following Ciarlet. Collection of
different finite elements.

The logo for the DUNE project, featuring the word "DUNE" in a bold, orange, sans-serif font. The background of the logo is a landscape of sand dunes under a blue sky.

<http://www.dune-project.org/>

DUNE ecosystem

- ▶ modular structure
- ▶ write your own DUNE modules
- ▶ available under different licenses

Discretization Modules:

dune-pdelab: discretization module based on dune-localfunctions.

dune-fem: Alternative implementation of finite element functions.

dune-functions: A new initiative to provide unified interfaces for functions and function spaces.

External Modules:

Kaskade 7: Simulation Suite – uses Dune for the grid and linear algebra infrastructure.

DuMu^x: simulations of flow and transport processes in porous media. Development is in an early state.

dune-grid-glu: allows to compute overlapping and nonoverlapping couplings of Dune grids, as required for most domain decomposition algorithms.

dune-subgrid: allows you to work on a subset of a given DUNE grid.

dune-networkgrid: is a grid manager for a network of 1d entities in a 3d world.

dune-prismgrid: is a tensorgrid of a 2D simplex grid and a 1D grid.

dune-cornerpoint: a cornerpoint mesh, compatible with the grid format of the ECLIPSE reservoir simulation software.

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Part II

Dune Course: Grid Module

People think that computer science is the art of geniuses but the actual reality is the opposite, just many people doing things that build on each other, like a wall of mini stones.

— Donald E. Knuth

Why Grids?

Weak formulation of boundary value problem:

$$\text{Find } u \in U \text{ s.t. } a(u, v) = l(v) \quad \forall v \in V.$$

$a(u, v)$ and $l(v)$ are (bi)linear forms, e.g.

$$a(u, v) = \int_{\Omega} \nabla u \cdot \nabla v \, dx,$$

with spatial domain $\Omega \subset \mathbb{R}^d$.

How to evaluate the integrals?

- ▶ No analytic integrals available for $a(u, v)$ and $l(v)$.
- ▶ No analytic description for the shape of $\Omega \subset \mathbb{R}^d$.

→ Use a numerical quadrature scheme!

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Numerical Quadrature

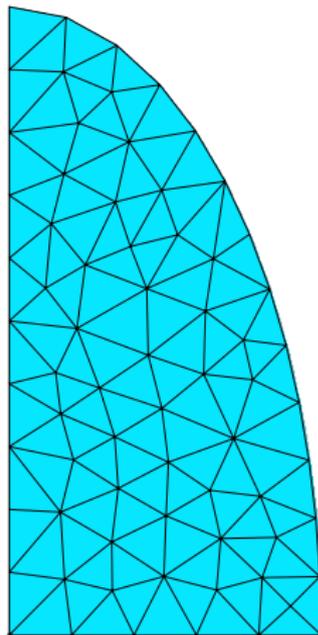
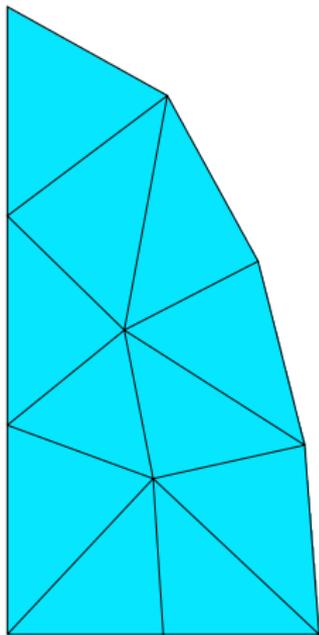
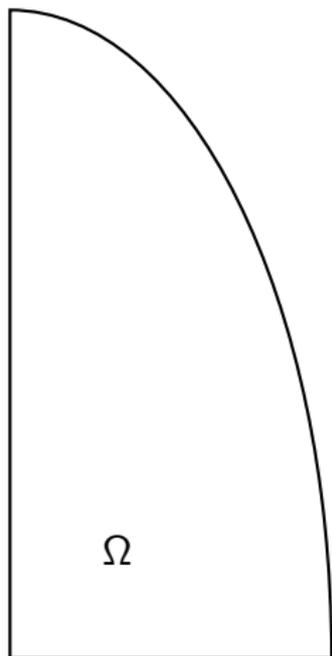
- ▶ Approximate integral by a weighted sum of function evaluations at sampling points:

$$\int_{\Omega} f(x) dx \approx \sum_{i=1}^N w_i f(x_i)$$

with weights w_i and sampling points x_i , $i = 1, \dots, N$.

- ▶ Different construction methods for w_i and x_i
 - ▶ Typically uses series of polynomials (Legendre, Lagrange, Lobatto, ...).
 - ▶ Exact for polynomial f up to a predefined order.
- ▶ Quadrature scheme depends on Ω !
 - ▶ Most schemes only available for simple shapes (triangle, square, tetrahedron, ...).
 - ▶ Quadrature on complicated shapes done by approximating Ω by small volumes of regular shape.

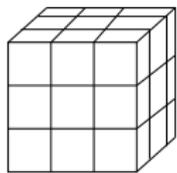
Computational Grid



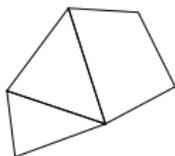
The DUNE Grid Module

- ▶ The DUNE Grid Module is one of the five DUNE Core Modules.
- ▶ DUNE wants to provide an interfaces for grid-based methods. Therefore the concept of a *Grid* is the central part of DUNE.
- ▶ `dune-grid` provides the interfaces, following the concept of a *Grid*.
- ▶ Its implementation follows the three *design principles* of DUNE:
 - Flexibility:** Separation of data structures and algorithms.
 - Efficiency:** Generic programming techniques.
 - Legacy Code:** Reuse existing finite element software.

Designed to support a wide range of Grids



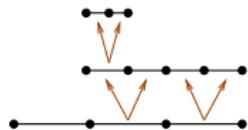
structured



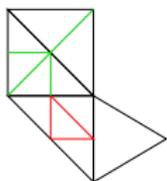
conforming



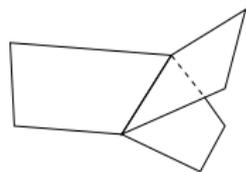
non conforming



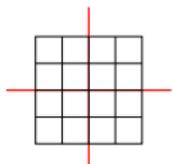
nested, 1D



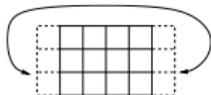
red-green, bisektion



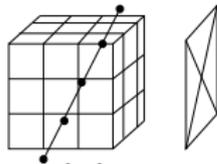
manifolds



parallel data decomposition



periodic



mixed dimensions

DUNE Grid Interface¹ Features

- ▶ Provide abstract interface to grids with:
 - ▶ Arbitrary dimension embedded in a world dimension,
 - ▶ multiple element types,
 - ▶ conforming or nonconforming,
 - ▶ hierarchical, local refinement,
 - ▶ arbitrary refinement rules (conforming or nonconforming),
 - ▶ parallel data distribution and communication,
 - ▶ dynamic load balancing.
- ▶ Reuse existing implementations (ALU, UG, Alberta) + special implementations (YaspGrid, FoamGrid).
- ▶ Meta-Grids built on-top of the interface (GeometryGrid, SubGrid, MultiDomainGrid)

¹Bastian, Blatt, Dedner, Engwer, Klöfkor, Kornhuber, Ohlberger, Sander: *A generic grid interface for parallel and adaptive scientific computing. Part I: Implementation and tests in DUNE*. Computing, 82(2-3):121–138, 2008.

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The Grid

Views to the Grid

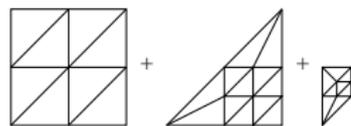
Entities

Attaching Data to the Grid

Further Reading

The Grid

A formal specification of grids is required to enable an accurate description of the grid interface.



Hierarchic Grid

In DUNE a *Grid* is always a hierarchic grid of dimension d , existing in a w dimensional space.

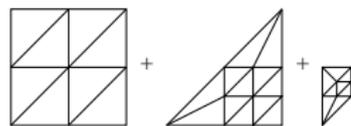
The Grid is parametrised by

- ▶ the dimension d ,
- ▶ the world dimension w
- ▶ and the maximum level J .

Within todays excercises we will always assume $d = w$ and we will ignore the hierarchic structure of the grids we deal with.

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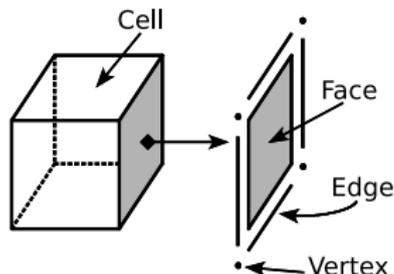
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The Grid... A Container of Entities...

In the DUNE sense a *Grid* is a container of entities:



- ▶ vertices ,
- ▶ edges ,
- ▶ faces ,
- ▶ cells , ...

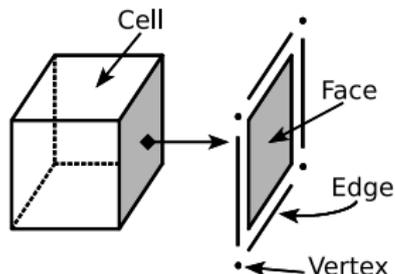
In order to do dimension independent programming, we need a dimension independent naming for different entities.

We distinguish entities according to their codimension.

Entities of $\text{codim} = c$ contain subentities of $\text{codim} = c + 1$. This gives a recursive construction down to $\text{codim} = d$.

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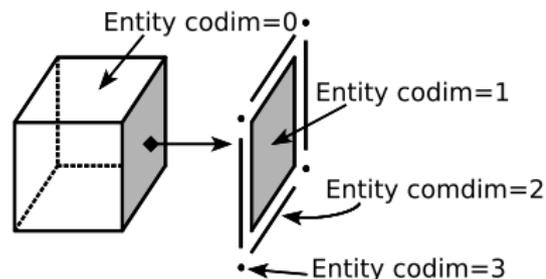
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The Grid... A Container of Entities...

In the DUNE sense a *Grid* is a container of entities:



- ▶ vertices (*Entity codim* = d),
- ▶ edges (*Entity codim* = $d - 1$),
- ▶ faces (*Entity codim* = 1),
- ▶ cells (*Entity codim* = 0), ...

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The DUNE Grid Interface

The DUNE Grid Interface is a collection of classes and methods

```
#include <dune/grid/yaspgrid.hh>

...

using Grid = Dune::YaspGrid<2>;
Grid grid({4,4},{1.0,1.0},{false,false});
auto gv = grid.leafGridView();
for (const auto& cell : elements(gv)) {
    // do something
}
```

We will now get to know the most important classes and see how they interact.

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Modifying a Grid

The DUNE Grid interface follows the *View-only* Concept.

View-Only Concept

- ▶ Views offer (read-only) access to the data
 - ▶ Read-only access to grid entities allow the consequent use of `const`.
 - ▶ Access to entities is only through iterators for a certain view.
→ *This allows on-the-fly implementations.*
- ▶ Data can only be modified in the primary container (*the Grid*)

Modification Methods:

- ▶ Global Refinement
- ▶ Local Refinement & Adaption
- ▶ Load Balancing

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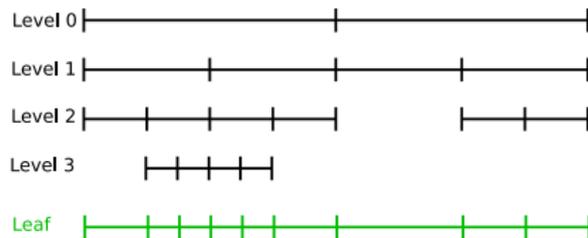
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Further Reading

Views to the Grid

A Grid offers two major views:



levelwise:

all entities associated with the same level.

Note: not all levels must cover the whole domain.

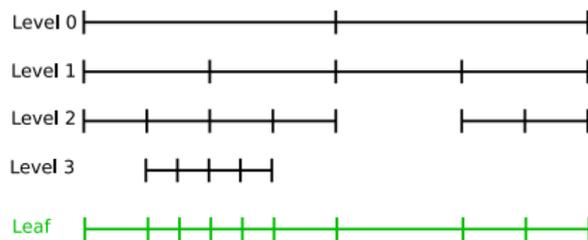
leafwise:

all leaf entities (entities which are not refined).

The leaf view can be seen as the projection of a levels onto a flat grid. It again covers the whole domain.

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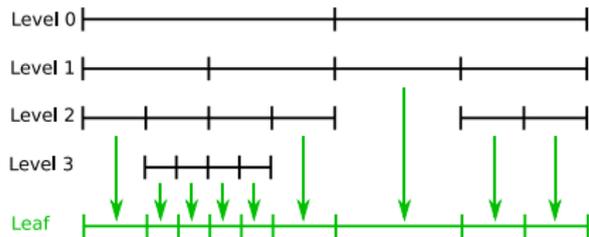
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Views to the Grid

Dune::GridView

- ▶ The `Dune::GridView` class consolidates all information depending on the current View.
- ▶ Every Grid must provide
 - ▶ `Grid::LeafGridView` and
 - ▶ `Grid::LevelGridView`.
- ▶ The Grid creates a new view every time you ask it for one, so you need to store a copy of it.
- ▶ Accessing the Views:
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Iterating over grid entities

Typically, most code uses the grid to iterate over some of its entities (e.g. cells) and perform some calculations with each of those entities.

- ▶ GridView supports iteration over all entities of one codimension.
- ▶ Iteration uses C++11 range-based for loops:

```
for (const auto& cell : elements(gv)) {  
    // do some work with cell  
}
```

- ▶ The type in front of `cell` is important:
 - ▶ If you create an entity in a range-based for loop, use `const auto&`.
 - ▶ In *all* other cases, use plain `auto`!

If you do not follow this advice, your program may crash in unpredictable ways.

Iteration functions

```
for (const auto& cell : elements(gv)) {  
    // do some work with cell  
}
```

Depending on the entities you are interested in, you can use one of the following functions:

```
// Iterates over cells (codim = 0)  
for (const auto& c : elements(gv))  
// Iterates over vertices (dim = 0)  
for (const auto& v : vertices(gv))  
// Iterates over facets (codim = 1)  
for (const auto& f : facets(gv))  
// Iterates over edges (dim = 1)  
for (const auto& e : edges(gv))  
  
// Iterates over entities with a given codimension (here: 2)  
for (const auto& e : entities(gv, Dune::Codim<2>{}))  
// Iterates over entities with a given dimension (here: 2)  
for (const auto& e : entities(gv, Dune::Dim<2>{}))
```

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Iterating over a grid view, we get access to the entities.

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for (const auto& cell : elements(gv)) {  
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- ▶ Entities cannot be modified.
- ▶ Entities can be copied and stored (but copies might be expensive!).
- ▶ Entities provide topological and geometrical information.

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Entities

An Entity E provides both topological information

- ▶ Type of the entity (triangle, quadrilateral, etc.).
- ▶ Relations to other entities.

and geometrical information

- ▶ Position of the entity in the grid.

Entity E is defined by . . .

- ▶ Reference Element $\hat{\Omega}$
- ▶ Transformation T_E

Mapping from $\hat{\Omega}$ into global coordinates.

`GridView::Codim<c>::Entity` implements the entity concept.

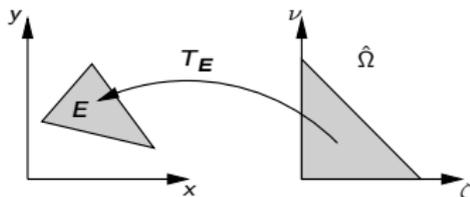
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and geometrical information

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Mapping from $\hat{\Omega}$ into global coordinates.

Entity E is defined by...

- ▶ Reference Element $\hat{\Omega}$
- ▶ Transformation T_E

`GridView::Codim<c>::Entity` implements the entity concept.

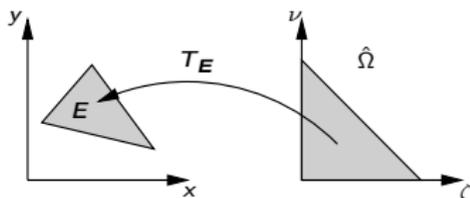
Entities

An Entity E provides both topological information

- ▶ Type of the entity (triangle, quadrilateral, etc.).
- ▶ Relations to other entities.

and geometrical information

- ▶ Position of the entity in the grid.



Mapping from $\hat{\Omega}$ into global coordinates.

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Storing Entities

GridView::Codim<c>::Entity

- ▶ Entities can be copied and stored like any normal object.
- ▶ Important: There can be *multiple* entity objects for a single logical grid entity (because they can be copied)
- ▶ *Memory expensive, but fast.*

GridView::Codim<c>::EntitySeed

- ▶ Store minimal information to find an entity again.
- ▶ Create like this:

```
auto entity_seed = entity.seed();
```

- ▶ The grid can create a new `Entity` object from an `EntitySeed`:

```
auto entity = grid.entity(entity_seed);
```

- ▶ *Memory efficient, but run-time overhead to recreate entity.*

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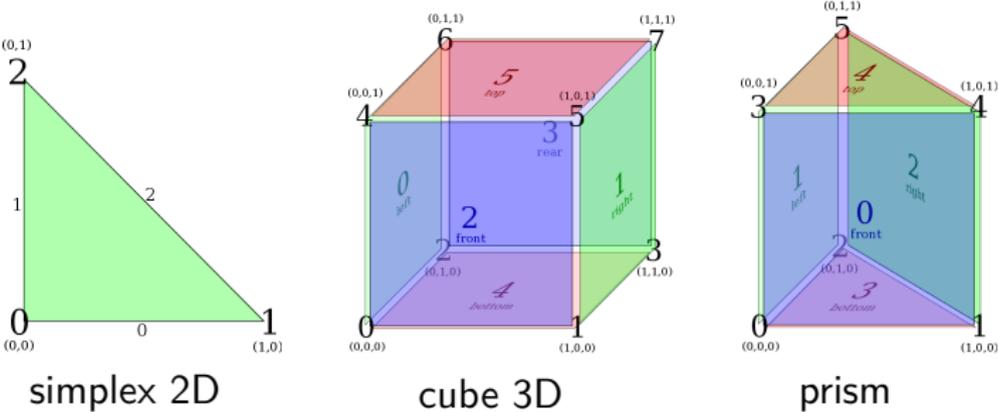
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Reference Elements

`Dune::GeometryType` identifies the type of the entities
Referenceelement.
It bundles a *topology ID* and the dimension.

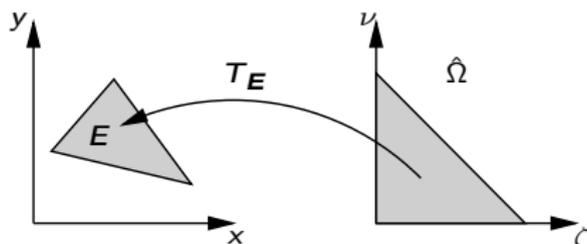
`Grid::Codim<c>::Entity::type()`
returns the `GeometryType` of the entity.



Geometry

Transformation T_E

- ▶ Maps from one space to another.
- ▶ Main purpose is to map from the reference element to global coordinates.
- ▶ Provides transposed inverse of the Jacobian ($J^{-T}(T_E)$).



Geometry Interface (I)

- ▶ Obtain Geometry from entity

```
auto geo = entity.geometry();
```

- ▶ Convert local coordinate to global coordinate

```
auto x_global = geo.global(x_local);
```

- ▶ Convert global coordinate to local coordinate

```
auto x_local = geo.local(x_global);
```

Geometry Interface (II)

- ▶ Get center of geometry in global coordinates

```
auto center = geo.center();
```

- ▶ Get number of corners of the geometry (e.g. 3 for a triangle)

```
auto num_corners = geo.corners();
```

- ▶ Get global coordinates of i -th geometry corner
($0 \leq i < \text{geo.corners}()$)

```
auto corner_global = geo.corner(i);
```

Geometry Interface (III)

- ▶ Get type of reference element

```
auto geometry_type = geo.type(); // square, triangle, ...
```

- ▶ Find out whether geometry is affine

```
if (geo.affine()) {  
    // do something optimized  
}
```

- ▶ Get volume of geometry in global coordinate system

```
auto volume = geo.volume();
```

- ▶ Get integration element for a local coordinate (required for numerical integration)

```
auto mu = geo.integrationElement(x_local);
```

Gradient Transformation

Assume

$$f : \Omega \rightarrow \mathbb{R}$$

evaluated on a cell E , i.e. $f(T_E(\hat{x}))$.

The gradient of f is then given by

$$J_T^{-T}(\hat{x}) \hat{\nabla} f(T_E(\hat{x})) :$$

```
auto x_global = geo.global(x_local);
auto J_inv = geo.jacobianInverseTransposed(x_local);
auto tmp = gradient(f)(x_global); // gradient(f) supplied by user
auto gradient = tmp;
J_inv.mv(tmp, gradient);
```

Quadrature Rules

- ▶ guarantees exact integration of polynomial functions of order k .
- ▶ Part of dune-geometry
- ▶ Given `Geometry` and quadrature order, we obtain the `QuadratureRule`.
- ▶ A `QuadratureRule` is a range of `QuadraturePoint`.
- ▶ `QuadraturePoint` gives weight and position:
`QuadraturePoint::weight()` `QuadraturePoint::position()`

Note: Simple access to `QuadratureRule` provided by `dune-pdelab`

```
#include <dune/pdelab/common/quadraturerules.hh>

...

auto quad = Dune::PDELab::quadratureRule(geometry, order);
for (const auto& qp : quad)
{
    auto x_local = qp.position();
    auto w = qp.weight();
}
```

Quadrature Rules

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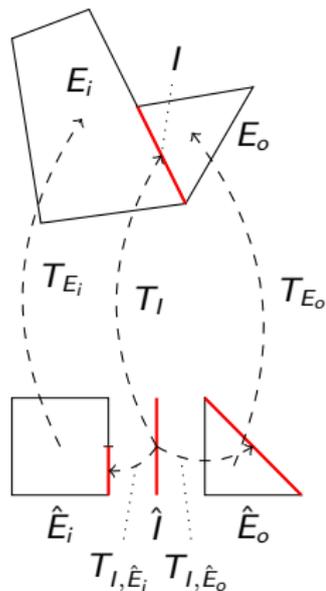
Example: Average of a function f on a GridView

$$\frac{1}{|\Omega|} \int_{\Omega} f(x) dx \approx \frac{1}{\sum_{E \in GV} |e|} \sum_{E \in GV} \sum_{i \in QR} f(T_e(x_i)) w_i |\det J_E^T(x_i)|^{1/2}$$

```
double value = 0.0, volume = 0.0;
for (const auto& cell : elements(gv)) {
    auto geo = cell.geometry();
    // integrate with numerical quadrature
    for (auto& qp : Dune::PDELab::quadratureRule(geo,2)) {
        auto x_local = qp.position();
        auto x_global = geo.global(x_local);
        // accumulate integral contribution
        value += f(x_global) *
                qp.weight() * geo.integrationElement(x_local);
    }
    volume += geo.volume();
}
std::cout << "Average:_" << value / volume << std::endl;
```

Intersections

- ▶ Grids may be non conforming.
- ▶ Entities can intersect with neighbours and boundary.
- ▶ Represented by Intersection objects.
- ▶ Intersections hold topological and geometrical information.
- ▶ Intersections depend on the view:
- ▶ **Note:** Intersections are always of codimension 1!



Intersection Interface

- ▶ Is this an intersection with the domain boundary?

```
bool b = intersection.boundary();
```

- ▶ Is there an entity on the outside of the intersection?

```
bool b = intersection.neighbor();
```

- ▶ Get the cell on the inside

```
auto inside_cell = intersection.inside();
```

- ▶ Get the cell on the outside

```
// Do this only if intersection.neighbor() == true  
auto outside_cell = intersection.outside();
```

Intersection: Geometries

- ▶ Get mapping from intersection reference element to global coordinates

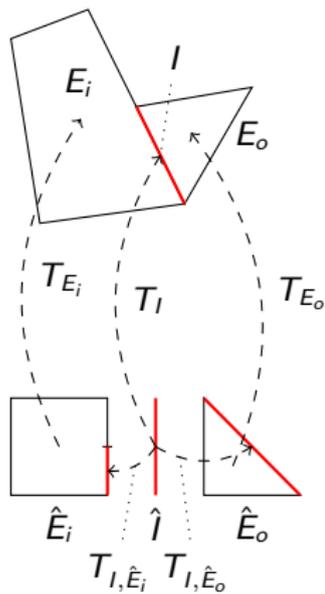
```
auto world_geo =  
    intersection.geometry();
```

- ▶ Get mapping from intersection reference element to reference element of inside cell

```
auto inside_geo =  
    intersection.geometryInInside();
```

- ▶ Get mapping from intersection reference element to reference element of outside cell

```
auto outside_geo =  
    intersection.geometryInOutside();
```



Intersection: Normals

- ▶ Get unit outer normal for local coordinate.

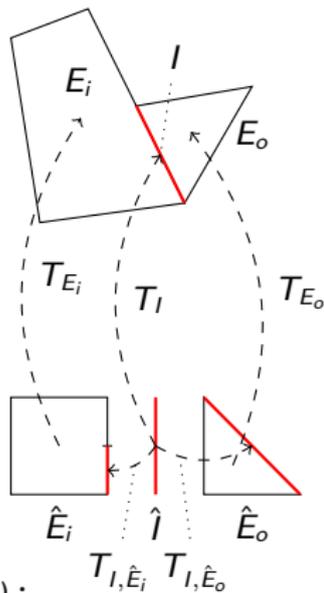
```
auto unit_outer_normal =  
    intersection.unitOuterNormal(x_local);
```

- ▶ Get unit outer normal for center of intersection (good for affine geometries).

```
auto unit_outer_normal =  
    intersection.centerUnitOuterNormal();
```

- ▶ Get unit outer normal scaled with integration element (convenient for numerical quadrature).

```
auto integration_outer_normal =  
    intersection.integrationOuterNormal(x_local);
```



Example: Iterating over intersections

In order to iterate over the intersections of a given grid cell with respect to some GridView, use a range-based for loop with the argument `intersections(gv,cell)`.

The following code iterates over all cells in a GridView and over all intersections of each cell:

```
for (const auto& cell : elements(gv))
  for (const auto& is : intersections(gv,cell)) {
    if (is.boundary()) {
      // handle potential Neumann boundary
    }
    if (is.neighbor()) {
      // code for Discontinuous Galerkin or Finite Volume
    }
  }
```

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Attaching Data to the Grid

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Attaching Data to the Grid

For computations we need to associate data with grid entities:

- ▶ spatially varying parameters,
- ▶ entries in the solution vector or the stiffness matrix,
- ▶ polynomial degree for p -adaptivity
- ▶ status information during assembling
- ▶ ...

Attaching Data to the Grid

For computations we need to associate data with grid entities:

- ▶ Allow association of FE computations data with subsets of entities.
- ▶ Subsets could be “vertices of level l ”, “faces of leaf elements”,
...
- ▶ Data should be stored in arrays for efficiency.
- ▶ Associate index/id with each entity.

Indices and Ids

Index Set: provides a map $m : E \rightarrow \mathbb{N}_0$, where E is a subset of the entities of a grid view.

We define the subsets E_g^c of a grid view

$$E_g^c = \{e \in E \mid e \text{ has codimension } c \text{ and geometry type } g\}.$$

- ▶ unique within the subsets E_g^c .
- ▶ consecutive and zero-starting within the subsets E_g^c .
- ▶ distinct leaf and a level index.

Id Set: provides a map $m : E \rightarrow \mathbb{I}$, where \mathbb{I} is a discrete set of ids.

- ▶ unique within E .
- ▶ ids need not to be consecutive nor positive.
- ▶ persistent with respect to grid modifications.

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- ▶ ids need not to be consecutive nor positive.
- ▶ persistent with respect to grid modifications.

Example: Store the lengths of all edges

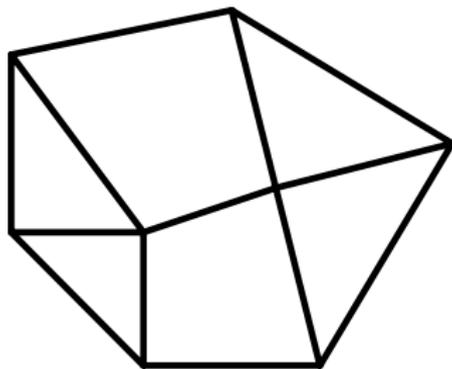
The following example demonstrates how to

- ▶ query an index set for the number of contained entities of a certain codimension (so that we can allocate a vector of correct size).
- ▶ obtain the index of a grid entity from an index set and use it to store associated data.

```
auto& index_set = gv.indexSet();  
// Create a vector with one entry for each edge  
auto edge_lengths = std::vector<double>(index_set.size(1));  
// Loop over all edges and store their length  
for (const auto& edge : edges(gv))  
    lengths[index_set.index(edge)] = edge.geometry().volume();
```

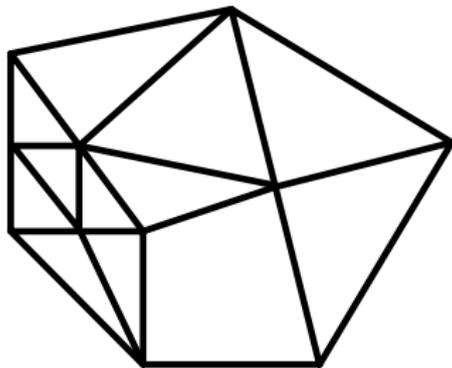
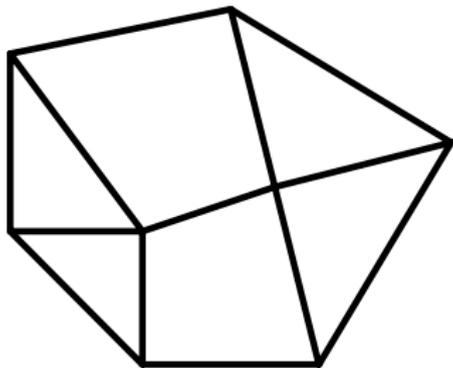
Example: 2D Multi-Element Grid – Indices

Locally refined grid:



Example: 2D Multi-Element Grid – Indices

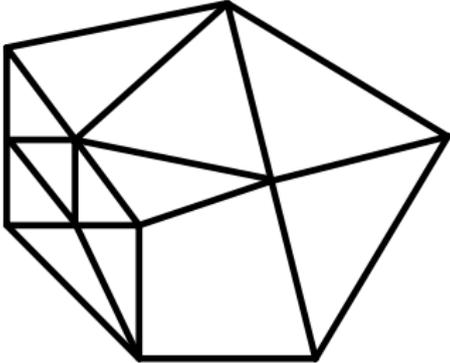
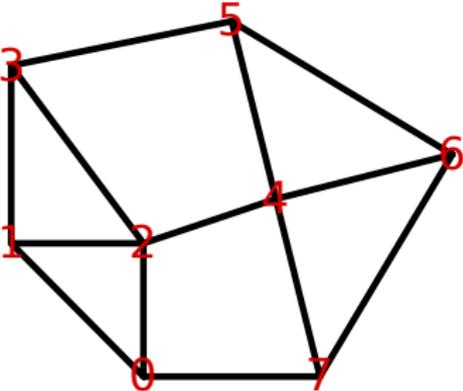
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Example: 2D Multi-Element Grid – Indices

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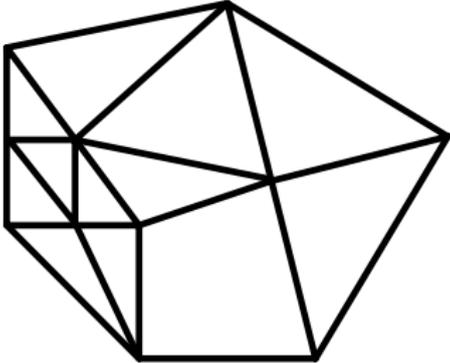
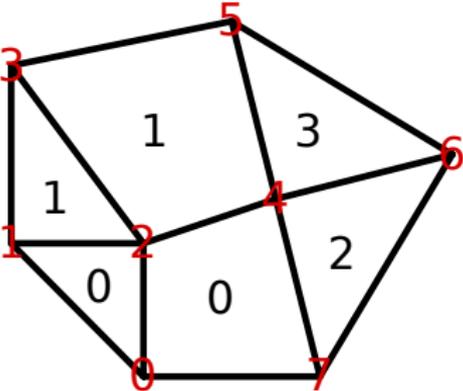


Consecutive index for vertices

Example: 2D Multi-Element Grid – Indices

Locally refined grid:

Indices:

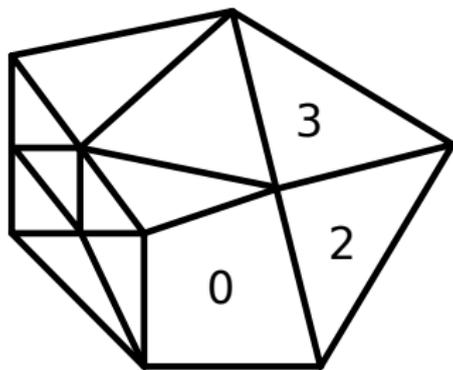
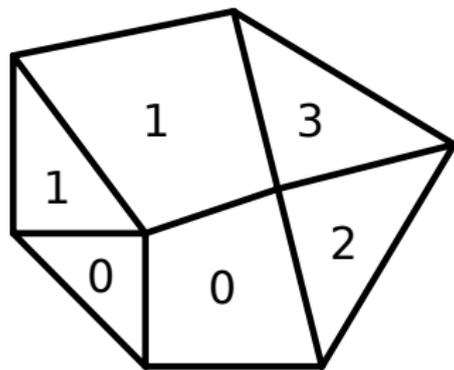


... and cells

Example: 2D Multi-Element Grid – Indices

Locally refined grid:

Indices:

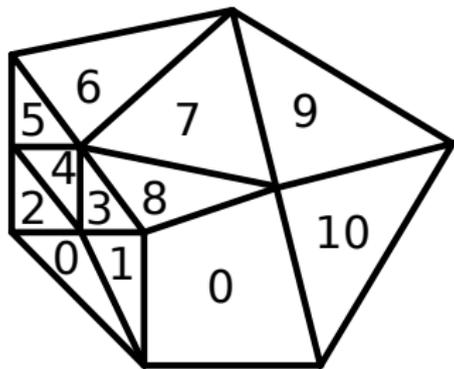
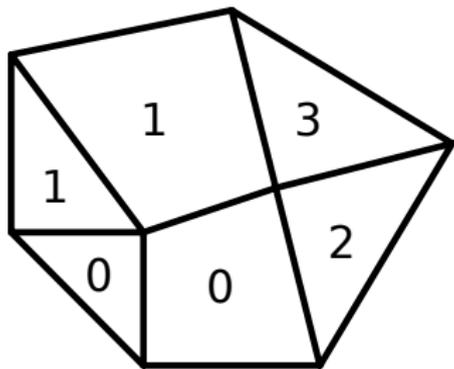


Old cell indices on refined grid

Example: 2D Multi-Element Grid – Indices

Locally refined grid:

Indices:

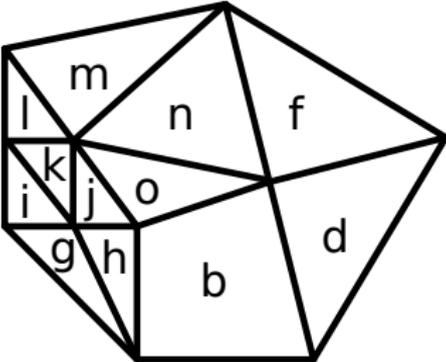
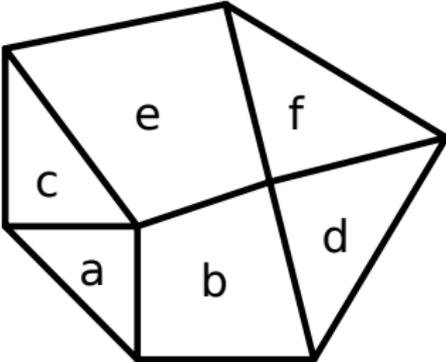


Consecutive cell indices on coarse and refined grid

Example: 2D Multi-Element Grid – Indices

Locally refined grid:

Ids:



Persistent Ids on coarse and refined grid

Mapper

Mappers extend the functionality of Index Sets.

- ▶ associate data with an arbitrary subsets $E' \subseteq E$ of the entities E of a grid.
- ▶ the data $D(E')$ associated with E' is stored in an array.
- ▶ map from the consecutive, zero-starting index $I_{E'} = \{0, \dots, |E'| - 1\}$ to the data set $D(E')$.

Mappers can be easily implemented upon the Index Sets and Id Sets.

You will be using the

`Dune::MultipleCodimMultipleGeomTypeMapper<GridView,Layout>`.

Example: Mapper (I)

```
#include <dune/grid/common/mcmgmapper.hh>
...

typedef Dune::SomeGrid::LeafGridView GridView;
...

/* create a mapper*/
// Layout description (equivalent to Dune::MCMGElementLayout)
template<int dim>
struct CellData {
    bool contains (Dune::GeometryType gt) {
        return gt.dim() == dim;
    }
};

// mapper for elements (codim=0) on leaf
using Mapper =
    Dune::MultipleCodimMultipleGeomTypeMapper<GridView, CellData>;
Mapper mapper(gridview);
```

Example: Mapper (II)

```
using Mapper =
    Dune::MultipleCodimMultipleGeomTypeMapper<GridView, CellData>;
Mapper mapper(gridview);

/* setup sparsity pattern */
// iterate over the leaf
for (const auto& entity : elements(gridview))
{
    int index = mapper.index(entity);
    // iterate over all intersections of this cell
    for (const auto& i : intersections(gridview, entity))
    {
        // neighbor intersection
        if (i.neighbor()) {
            int nindex = mapper.index(i.outside());
            matrix[index].insert(nindex);
        }
    }
}
```

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Further Reading

Further Reading

What we didn't discuss. . .

- ▶ grid creation
- ▶ I/O
- ▶ grid adaptation
- ▶ parallelization
- ▶ further specialized methods

Further Reading

Literature



P. Bastian, M. Blatt, A. Dedner, C. Engwer, R. Klöfkorn, M. Ohlberger, O. Sander.

A Generic Grid Interface for Parallel and Adaptive Scientific Computing. *Part I: Abstract Framework.*

Computing, 82(2–3), 2008, pp. 103–119.



P. Bastian, M. Blatt, A. Dedner, C. Engwer, R. Klöfkorn, M. Ohlberger, O. Sander.

A Generic Grid Interface for Parallel and Adaptive Scientific Computing. *Part II: Implementation and Tests in DUNE.*

Computing, 82(2–3), 2008, pp. 121–138.